# A Transformational Property of 2-Dimensional Density Matrices

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**Introduction.** This note derives from recent work related to decoherence models described by Zurek<sup>1</sup> and Albrecht.<sup>2</sup> In both models a qubit S interacts with a high-dimensional system  $\mathcal{E}$ —the "environment." The dynamically evolved state of S is described by a 2×2 hermitian matrix, the reduced density matrix  $\mathbb{R}_S$ . The following discussion was motivated by issues that arose in that connection.

Structure of the characteristic polynomial. Let  $\mathbb{D}$  be diagonal

$$\mathbb{D} = \begin{pmatrix} \lambda_1 & 0\\ 0 & \lambda_2 \end{pmatrix}$$

and let its characteristic polynomial be denoted  $p(x) \equiv \det(\mathbb{D} - x\mathbb{I})$ . Obviously

$$p(x) = (\lambda_1 - x)(\lambda_2 - x)$$
  
=  $x^2 - (\lambda_1 + \lambda_2)x + \lambda_1\lambda_2$   
=  $x^2 - (\lambda_1 + \lambda_2)x + \frac{1}{2}[(\lambda_1 + \lambda_2)^2 - (\lambda_1^2 + \lambda_2^2)]$   
=  $x^2 - T_1x + \frac{1}{2}(T_1^2 - T_2)$  (1)

where  $T_n \equiv \operatorname{tr} \mathbb{D}^n$ . More than fifty years ago I had occasion to develop—and have many times since had occasion to use—a population of trace formulæ of which (1) is a special instance.<sup>3</sup>Remarkably, the formulæ in question pertain to *all* square matrices, and so in particular does (1): the diagonality assumption can be dispensed with. For *any* 2×2 M we have

$$p(x) = x^2 - T_1 x + \frac{1}{2} (T_1^2 - T_2) \quad \text{with} \quad T_n \equiv \operatorname{tr} \mathbb{M}^n \tag{2}$$

 $<sup>^1</sup>$  W. H. Zurek, "Environment-induced superselection rules," Phys. Rev. D **26**, 1862-1880 (1982); M. Schlosshauer, *Decoherence & the Quantum-to-Classical Transition* (2008), §2.10.

<sup>&</sup>lt;sup>2</sup> A. Albrecht, "Investigating decoherence in a simple model," Phys. Rev. D **46**, 5504-5520 (1992).

 $<sup>^{3}</sup>$  See, for example, "A mathematical note: Algorithm for the efficient evaluation of the trace of the inverse of a matrix" (December 1996), where (1) appears as illustrative equation (12).

from which it follows in particular that for any such  $\mathbb{M}$ 

$$\det \mathbb{M} = \frac{1}{2} (T_1^2 - T_2) \tag{3}$$

**Application to density matrices.** Density matrices are positive-definite hermitian matrices with unit trace, and *vice versa*. Hermiticity insures that the eigenvalues of such a matrix  $\mathbb{R}$  are real, positive definiteness

$$(\alpha | \mathbb{R} | \alpha) > 0$$
 : all column vectors  $| \alpha \rangle$ 

requires that they be non-negative, and since they are required to sum to unity each must fall within the unit interval:  $0 \leq \lambda_1, \lambda_2 \leq 1$ . From this condition it follows that

$$0 \le \lambda_i^2 \le \lambda_i \le 1$$
 with  $\lambda_i^2 = \lambda_i$  iff  $\lambda_i = 0$  else 1

From  $\lambda_1 + \lambda_2 = 1$  is follows moreover that if one  $\lambda$  vanishes the other must be unity. We therefore have

$$\operatorname{tr} \mathbb{R} = 1$$
 and  $0 < \operatorname{tr} \mathbb{R}^2 \le 1$ :   
  $\begin{cases} \operatorname{mixed \ cases} \\ \operatorname{pure \ cases} \end{cases}$ 

.

In mixed cases the spectral decomposition of  $\mathbb R$  reads

$$\mathbb{R}_{\text{mixed}} = \lambda_1 |r_1| (r_1| + \lambda_2 |r_2) (r_2|$$

where  $|r_1\rangle$  and  $|r_2\rangle$  are orthonormal eigenvectors, while in pure cases the spectral decomposition trivializes:

$$\mathbb{R}_{\text{pure}} = 1 |r_1| (r_1| + 0 |r_2|) (r_2| = |r_1| (r_1|)$$

The characteristic polynomials of 2-dimensional density matrices have the structure

$$p(x) = x^2 - x + \frac{1}{2}(1 - T_2)$$

which gives

$$\lambda_{\pm} = \frac{1}{2} \left[ 1 \pm \sqrt{2T_2 - 1} \right] \tag{4}$$

The invariable reality of  $\lambda_{\pm}$  implies that in all cases

$$\frac{1}{2} \le T_2 \le 1$$

(which sharpens the condition  $0 < \operatorname{tr} \mathbb{R}^2 \leq 1$  stated above): maximal mixing arises at the lower bound (where the eigenvalues become equal and the spectrum degenerate), purity at the upper bound. Finally, (3) has become

$$\det \mathbb{R} = \frac{1}{2}(1 - T_2) \tag{5}$$

2

# **Trace-preserving transformations**

Transformations that preserve both  $T_1$  and  $T_2$ . The most general 2-dimensional density matrix can be written

$$\mathbb{R} = \begin{pmatrix} p_1 & re^{+i\varphi} \\ re^{-i\varphi} & p_2 \end{pmatrix}$$

of which the eigenvalues are

$$\lambda_{\pm} = \frac{1}{2} \Big[ (p_1 + p_2) \pm \sqrt{4r^2 + (p_1 - p_2)^2} \Big] \\ = \frac{1}{2} \Big[ 1 \pm \sqrt{4r^2 + (p_1 - p_2)^2} \Big]$$
(6)

while

$$\det \mathbb{R} = p_1 p_2 - r^2 \tag{7}$$

Comparison of (6) with (4) supplies

$$T_2 = 2r^2 + 1 + \frac{1}{2} [(p_1 - p_2)^2 - 1]$$
(8.1)

while comparison of (7) with (5) supplies

$$T_2 = 2r^2 + 1 - 2p_1p_2 \tag{8.2}$$

The equivalence of equations (8) follows from

$$\frac{1}{2} \left[ (p_1 - p_2)^2 - 1 \right] = \frac{1}{2} \left[ (p_1 - p_2)^2 - (p_1 + p_2)^2 \right] = -2p_1 p_2 \tag{9}$$

We are interested in transformations

$$\mathbb{R} = \begin{pmatrix} p_1 & re^{+i\varphi} \\ re^{-i\varphi} & p_2 \end{pmatrix} \longrightarrow \tilde{\mathbb{R}} = \begin{pmatrix} p_1 + a & s \\ s & p_2 - a \end{pmatrix}$$

that preserve  $T_2$  (the preservation of  $T_1$  has been prearranged). This—by (5) is equivalent to asking for transformations that preserve det  $\mathbb{R}$ . We proceed stepwise. STEP 1: Trivially

$$\det \begin{pmatrix} p_1 & re^{+i\varphi} \\ re^{-i\varphi} & p_2 \end{pmatrix} = \det \begin{pmatrix} p_1 & r \\ r & p_2 \end{pmatrix}$$

STEP 2: Show by (Mathematica-assisted) calculation that

$$\det \begin{pmatrix} p_1 & r \\ r & p_2 \end{pmatrix} = \det \begin{pmatrix} p_1 + a & r + s \\ r + s & p_2 - a \end{pmatrix}$$

if  $s = -r \pm \sqrt{r^2 + a(p_2 - p_1) - a^2} \equiv -r \pm R$ . STEP 3: Observe that trivially

$$\det \begin{pmatrix} p_1 + a & \pm R \\ \pm R & p_2 - a \end{pmatrix} = \det \begin{pmatrix} p_1 + a & \pm Re^{\pm i\vartheta} \\ \pm Re^{-i\vartheta} & p_2 - a \end{pmatrix}$$

The net implication is that the matrices

$$\tilde{\mathbb{R}}(a,\vartheta) = \begin{pmatrix} p_1 + a & e^{+i\vartheta}\sqrt{r^2 + a(p_2 - p_1) - a^2} \\ e^{-i\vartheta}\sqrt{r^2 + a(p_2 - p_1) - a^2} & p_2 - a \end{pmatrix}$$

are—for all a and all  $\vartheta$ —tracewise (and  $\therefore$  determinantally) identical<sup>4</sup> to  $\mathbb{R}$ , and give back  $\mathbb{R}$  as a special case:

 $\tilde{\mathbb{R}}(0,\varphi) = \mathbb{R}$ 

The previous  $\pm$  has been absorbed into the definition of  $\vartheta$ , and the unit trace presumption entails  $p_1 + p_2 = 1$ .

Trace invariance implies—by (2)—that of the characteristic polynomial, whence of the eigenvalues (6), which by (9) can be written

$$\lambda_{\pm} = \frac{1}{2} \left[ 1 \pm \sqrt{1 - 4(p_1 p_2 - r^2)} \right]$$

and give  $\lambda_+\lambda_- = p_1p_2 - r^2 = \det \mathbb{R}(a, \vartheta)$ . Positive semi-definiteness (which presumes reality) is seen to require

$$0 \le 1 - 4(p_1 p_2 - r^2) \le 1$$

The first inequality  $1 - 4p_1p_2 \leq 4r^2$  poses no constraint upon  $r^2$ , since  $p_1p_2$  ranges on  $[0, \frac{1}{4}]$  as  $\{p_1, p_2\}$  partition the unit interval, giving  $0 \leq 1 - 4p_1p_2$ . The second inequality can be written  $r^2 \leq p_1p_2$ , which entails

$$-r_{\max} \leq r \leq +r_{\max}$$
 with  $r_{\max} = \sqrt{p_1 p_2} = \text{geometric mean} \leq \frac{1}{2}$ 

We note that while spectral positivity implies  $\lambda_+\lambda_- = \det \mathbb{R} > 0$ , the converse is not true:  $\det \mathbb{R} > 0$  would result if both eigenvalues were *negative*. It is, therefore, somewhat accidental that in the present context the spectral positivity condition *can* be formulated  $\det \mathbb{R} = p_1 p_2 - r^2 > 0$ .

Spectral stability does not imply stability of the eigenvectors, though preservation of hermiticity ensures that the eigenvectors (except in spectrally degenerate cases) do remain orthogonal. I propose to describe the normalized eigenfunctions of  $\mathbb{R}(a, \vartheta)$ . But those turn out to be fairly intricate, and their structure not at all obvious, so I will take a moment to describe how those results were obtained.

The (unnormalized) symbolic eigenvectors supplied by *Mathematica* are of the asymmetric form

$$e_1 = \begin{pmatrix} x_1 \\ 1 \end{pmatrix}, \quad e_2 = \begin{pmatrix} x_2 \\ 1 \end{pmatrix}$$
(10.1)

<sup>&</sup>lt;sup>4</sup> I understand this phrase to mean " $T_1$  and  $T_2$ -preserving."

### **Trace-preserving transformations**

But orthonormal vectors in complex 2-space can invariably be displayed<sup>5</sup>

$$u_1 = e^{i\xi_1} \cdot \begin{pmatrix} \cos \alpha \\ +\sin \alpha \cdot e^{i\beta} \end{pmatrix}, \quad u_2 = e^{i\xi_2} \cdot \begin{pmatrix} \sin \alpha \\ -\cos \alpha \cdot e^{i\beta} \end{pmatrix}$$

We observe that if in  $u_2$  we flip the elements and change a sign we obtain a vector proportional to  $u_1$  (and *vice versa*). So as an alternative to (10.1) we have

$$f_1 = \begin{pmatrix} 1 \\ -x_2 \end{pmatrix}, \quad f_2 = \begin{pmatrix} 1 \\ -x_1 \end{pmatrix}$$
 (10.2)

Sums of eigenvectors are eigenvectors, so we obtain the symmetrized pair

$$g_1 = \begin{pmatrix} 1+x_1\\ 1-x_2 \end{pmatrix}, \quad g_1 = \begin{pmatrix} 1+x_2\\ 1-x_1 \end{pmatrix}$$
 (10.3)

That  $g_1 \perp g_2$  is seen to follow from  $e_1 \perp e_2 \iff 1 + \bar{x}_1 x_2 = 0 = 1 + \bar{x}_2 x_1$ . The norms of  $g_1$  and  $g_2$  are given by

$$|g_1| = \sqrt{2 + (x_1 + \bar{x}_1) - (x_2 + \bar{x}_2) + (\bar{x}_1 x_1 + \bar{x}_2 x_2)} |g_2| = \sqrt{2 - (x_1 + \bar{x}_1) + (x_2 + \bar{x}_2) + (\bar{x}_1 x_1 + \bar{x}_2 x_2)}$$

It is by this strategy that I have (with major assistance by *Mathematica*) constructed (and checked) the eigenvectors reported below:

In the context that motivated this discussion the off-diagonal elements of  $\tilde{\mathbb{R}}(a, \vartheta)$  are real; indeed, the constrants which we have been motivated to impose upon  $\{p_1, p_2, a\}$  render *all* elements real, so we can dispense with all allusions to the complex conjugates of variables. Introducing these auxiliary definitions

$$p = p_1 \quad \text{so} \quad p_2 = 1 - p$$

$$A(a) = \sqrt{r^2 + a(1 - 2p) - a^2} = \sqrt{r^2 + a(p_2 - p_1) - a^2}$$

$$B(a) = \frac{1}{2} - p - a \qquad = \frac{1}{2}(p_2 - p_1) - a$$

$$C = \frac{1}{2}\sqrt{1 + 4r^2 - 4p(1 - p)} = \frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)}$$

$$= \frac{1}{2}\sqrt{2T_2 - 1}$$

we look to the eigenvalues/vectors of the matrix

$$\mathbb{R}(a) = \begin{pmatrix} p_1 + a & A(a) \\ A(a) & p_2 - a \end{pmatrix}$$

which by design has the property that  $T_1 \equiv \operatorname{tr} \mathbb{R}(a) = 1$  and

$$T_2 \equiv \operatorname{tr} \mathbb{R}^2(a) = \operatorname{tr} \begin{pmatrix} p_1 & r \\ r & p_2 \end{pmatrix}^2 = 2r^2 + p_1^2 + p_2^2 = 1 + 2(r^2 - p_1 p_2) \quad : \quad \text{all } a$$

The eigenvalues are

$$\lambda_1 = \frac{1}{2} - C$$
 and  $\lambda_2 = \frac{1}{2} + C$ 

<sup>&</sup>lt;sup>5</sup> See Advanced Quantum Topics (2000), Chapter 1, page 5.

which are seen to supply  $\lambda_1 + \lambda_2 = 1 = T_1$  and

$$\lambda_1^2 + \lambda_2^2 = \frac{1}{2} + \frac{1}{2}C^2 = 1 + 2(r^2 - p_1p_2) = T_2$$

—as anticipated. The (unnormalized) eigenvectors are

$$g_1 = \begin{pmatrix} A - B - C \\ A + B - C \end{pmatrix}$$
 and  $g_2 = \begin{pmatrix} A - B + C \\ A + B + C \end{pmatrix}$ 

In confirmation of orthogonality we (with Mathematica's assistance) verify that

$$(A - B)^{2} - C^{2} + (A + B)^{2} - C^{2} = 2(A^{2} + B^{2} - C^{2}) = 0$$

The respective norms are

$$|g_1| = \sqrt{2[(A-C)^2 + B^2]} = 2\sqrt{(C-A)C} * |g_2| = \sqrt{2[(A+C)^2 + B^2]} = 2\sqrt{(C+A)C} *$$

where the equations marked  $\star$  follow from the previously-remarked circumstance that the definitions of A, B and C entail  $A^2 + B^2 - C^2 = 0$ .

In the case a = 0 we have

$$\begin{aligned} A(0) &= r \\ B(0) &= \frac{1}{2} - p \\ C &= \frac{1}{2}\sqrt{1 + 4r^2 - 4p(1-p)} = \frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)} \\ \mathbb{R}(0) &= \mathbb{R} = \begin{pmatrix} p_1 & r \\ r & p_2 \end{pmatrix} \end{aligned}$$

The values of  $T_1$  and  $T_2$  are unchanged (that was the whole point of this exercise!) and so also therefore do the values of  $\lambda_1$  and  $\lambda_2$ . The eigenvectors become

$$g_{01} = \begin{pmatrix} r - \frac{1}{2}(p_2 - p_1) - \frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)} \\ r + \frac{1}{2}(p_2 - p_1) - \frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)} \end{pmatrix}$$
$$g_{02} = \begin{pmatrix} r - \frac{1}{2}(p_2 - p_1) + \frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)} \\ r + \frac{1}{2}(p_2 - p_1) + \frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)} \end{pmatrix}$$

with norms

$$|g_{01}| = 2\sqrt{\left(-r + \frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)}\right)\frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)}}$$
$$|g_{02}| = 2\sqrt{\left(+r + \frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)}\right)\frac{1}{2}\sqrt{1 + 4(r^2 - p_1p_2)}}$$

In the trivial case r = a = 0 the preceding results give

$$A_0(0) = r$$
  

$$B_0(0) = \frac{1}{2} - p = \frac{1}{2}(p_2 - p_1)$$
  

$$C_0 = \frac{1}{2}\sqrt{1 - 4p(1 - p)} = \frac{1}{2}\sqrt{1 - 4p_1p_2}$$
  

$$= \frac{1}{2}(1 - 2p)$$

## Rotational aspects of the problem

$$\mathbb{R}_0(0) = \mathbb{R}_0 = \begin{pmatrix} p_1 & 0\\ 0 & p_2 \end{pmatrix}$$

The eigenvalues become

$$\lambda_1 = \frac{1}{2} - \frac{1}{2}(1 - 2p) = p \equiv p_1$$
  
$$\lambda_2 = \frac{1}{2} + \frac{1}{2}(1 - 2p) = 1 - p = p_2$$

as, of course, they must. The eigenvectors become

$$g_{001} = \begin{pmatrix} -\frac{1}{2}(1-2p) - \frac{1}{2}(1-2p) \\ +\frac{1}{2}(1-2p) - \frac{1}{2}(1-2p) \end{pmatrix} = \begin{pmatrix} p_1 - p_2 \\ 0 \end{pmatrix}$$
$$g_{002} = \begin{pmatrix} -\frac{1}{2}(1-2p) + \frac{1}{2}(1-2p) \\ +\frac{1}{2}(1-2p) + \frac{1}{2}(1-2p) \end{pmatrix} = \begin{pmatrix} 0 \\ p_1 - p_2 \end{pmatrix}$$

of which the predicted norms are

$$|g_{001}| = 2\sqrt{\frac{1}{2}(1-2p) \cdot \frac{1}{2}(1-2p)} = (1-2p) = p_1 - p_2$$
  
$$|g_{002}| = \text{ditto}$$

as again they must be.

**Rotational aspects of the problem.** Transformations that map density matrices to density matrices (*i.e.*, which preserve hermiticity, unit trace and positivity) have come to be called "operations," and can in general be accomplished by Kraus processes

$$\mathbb{R} \longrightarrow \mathbb{R}' = \sum_{k} \mathbb{A}_{k} \mathbb{R} \mathbb{A}_{k}^{+} \quad \text{where} \quad \sum_{k} \mathbb{A}_{k}^{+} \mathbb{A}_{k} = \mathbb{I}$$

We have been concerned with an operation that in the 2-dimensional case preserves not only  $T_1$  but also  $T_2$  (and therefore the spectrum). Kraus processes invariably preserve  $T_1$  but typcally do *not* preserve  $\{T_2, T_3, \ldots\}$  unless the set of Kraus matrices  $\{A_1, A_2, \ldots, A_n\}$  contains but a single member, when we have

$$\mathbb{R} \longrightarrow \mathbb{R}' = \mathbb{A} \mathbb{R} \mathbb{A}^+$$
 where  $\mathbb{A}^+ \mathbb{A} = \mathbb{I}$ , so  $\mathbb{A}$  is unitary

Such unitary similarity transformations do in any dimension preserve the traces of *all* powers of  $\mathbb{R}$ .

Hermiticity-preservation is by itself sufficient to ensure that the orthonormal eigenbasis  $\{|f_j\rangle : j = 1, 2, ..., n\}$  defined by  $\mathbb{R}'$  is a unitary transform of the eigenbasis  $\{|e_i\rangle : i = 1, 2, ..., n\}$  defined by  $\mathbb{R}$ —this even when  $\mathbb{R} \longrightarrow \mathbb{R}'$  is not unitary; we have

$$(f_j| = \sum_i (f_j|e_i)(e_i| \equiv \sum_i U_{ji}(e_i)$$

where

We have been working in a context in which the eigenvectors are (to within an irrelevant complex phase factor) real-valued, so our U-matrix is in fact a simple  $2 \times 2$  rotation matrix. And the transformations that have concerned us preserve not only orthonormality but also  $T_2$  (whence both eigenvalues). We conclude that the operation

$$\mathbb{R} = \begin{pmatrix} p_1 & r \\ r & p_2 \end{pmatrix}$$

$$\downarrow \qquad (11.1)$$

$$\mathbb{R}(a) = \begin{pmatrix} p_1 + a \\ \sqrt{r^2 + a(p_2 - p_1) - a^2} & p_2 - a \end{pmatrix}$$

$$= \begin{pmatrix} p_1 + a & A(a) \\ A(a) & p_2 - a \end{pmatrix}$$

contemplataed on page 4 amounts to no more nor less than a simple rotational transformation

$$\mathbb{R} = \begin{pmatrix} p_1 & r \\ r & p_2 \end{pmatrix} 
\downarrow$$

$$\mathbb{R}(\alpha) = \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix} \begin{pmatrix} p_1 & r \\ r & p_2 \end{pmatrix} \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} 
= \begin{pmatrix} p_1 \cos^2 \alpha + p_2 \sin^2 \alpha + r \sin 2\alpha & \frac{1}{2}(p_2 - p_1) \sin 2\alpha + r \cos 2\alpha \\ \frac{1}{2}(p_2 - p_1) \sin 2\alpha + r \cos 2\alpha & p_1 \sin^2 \alpha + p_2 \cos^2 \alpha - r \sin 2\alpha \end{pmatrix}$$
(11.2)

which, we observe, gives back  $\operatorname{tr} \mathbb{R}(\alpha) = p_1 + p_2 = 1$  and  $\operatorname{tr} \mathbb{R}^2(\alpha) = p_1^2 + p_2^2 + 2r^2$  for all values of  $\alpha$ .

Remarkably, the matrix elements  $\{p_1, p_2, r\}$  enter linearly into (11.2), but non-linearly into (11.1). Consistency must hinge on the  $\{p_1, p_2, r\}$ -dependence of  $\alpha$ . I show now how this comes about.

Working from either of the diagonal conditions

$$p_1 \cos^2 \alpha + p_2 \sin^2 \alpha + r \sin 2\alpha = p_1 + a$$
$$p_2 \cos^2 \alpha + p_1 \sin^2 \alpha - r \sin 2\alpha = p_2 - a$$

we write  $\tau \equiv \tan \alpha$  and use  $\sin^2 \alpha = \tau^2/(1+\tau^2)$ ,  $\cos^2 \alpha = 1/(1+\tau^2)$  to obtain

$$(a+p_1-p_2)\tau^2 - 2r\tau + a = 0 \tag{12.1}$$

of which the solutions are

$$\tau_{\pm} \equiv \tan \alpha_{\pm} = \frac{r \pm \sqrt{r^2 + a(p_2 - p_1) - a^2}}{a - (p_2 - p_1)} = \frac{r \pm A(a)}{a - (p_2 - p_1)}$$

8

# **Concluding remarks**

Working on the other hand from either of the (identical) off-diagonal conditions

$$\frac{1}{2}(p_2 - p_1)\sin 2\alpha + r\cos 2\alpha = A(a)$$

we use  $\sin 2\alpha = 2\tau/(1+\tau^2)$ ,  $\cos 2\alpha = (1-\tau^2)/(1+\tau^2)$  to obtain

$$(A+r)\tau^{2} + (p_{2} - p_{1})\tau + (A-r) = 0$$
(12.2)

where again  $A = A(a) = \sqrt{r^2 + a(p_2 - p_1) - a^2}$ . Notice that the equations (12) impose distinct quadratic conditions on  $\tau$ . The solutions of (12.2) are

$$\hat{\tau}_{\pm} = \frac{\pm (p_2 - p_1) - \sqrt{4r^2 + (p_2 - p_1)^2 - 4A^2}}{2(r+A)}$$
$$= \frac{\pm (p_2 - p_1) - ((p_2 - p_1) - 2a))}{2(r+A)}$$
$$= \begin{cases} \frac{a}{r+A} \\ \frac{(p_2 - p_1) - a}{r+A} \end{cases}$$

We have interest only in the *simultaneous* solution of (12.1) and (12.2). With *Mathematica*'s assistance we survey the possibilities, with the following results:

$$\begin{aligned} \tau_{+} &= \hat{\tau}_{+} &: \text{ true} \\ \tau_{+} &= \hat{\tau}_{-} &: \text{ false} \\ \tau_{-} &= \hat{\tau}_{+} &: \text{ false} \\ \tau_{-} &= \hat{\tau}_{-} &: \text{ false} \end{aligned}$$

The implication is that

$$\tau \equiv \tan \alpha = \frac{a}{r + \sqrt{r^2 + a(p_2 - p_1) - a^2}}$$
(13)

To check the accuracy or this result, we insert the implied evaluations of

$$\sin \alpha = \frac{\tau}{1+\tau^2}$$
 and  $\cos \alpha = \frac{1}{1+\tau^2}$ 

into (11.2) and, according to Mathematica, do in fact recover

$$\mathbb{R}(\alpha) = \begin{pmatrix} p_1 + a & \sqrt{r^2 + a(p_1 - p_2) - a^2} \\ \sqrt{r^2 + a(p_1 - p_2) - a^2} & p_2 - a \end{pmatrix}$$

**Concluding remarks.** Let the characteristic polynomial of an *n*-dimensional square matrix  $\mathbb{M}$  be written

$$\det(\mathbb{M} - x\mathbb{I}) = c_0 x^n + c_1 x^{n-1} + \dots + c_{n-1} x^1 + c_n$$

By the Cayley-Hamilton theorem  $c_0 \mathbb{M}^n + c_1 \mathbb{M}^{n-1} + \cdots + c_{n-1} \mathbb{M} + c_n \mathbb{I} = \mathbb{O}$ , so

$$\mathbb{M}^{n+1} = -(1/c_0) \Big\{ c_1 \mathbb{M}^n + c_2 \mathbb{M}^{n-1} \dots + c_{n-1} \mathbb{M}^2 + c_n \mathbb{M} \Big\}$$

of which the trace reads

$$T_{n+1} = -(1/c_0) \Big\{ c_1 T_n + c_2 T_{n-1} + \dots + c_{n-1} T_2 + c_n T_1 \Big\}$$

It is known,<sup>3,6</sup> moreover, that the coefficients  $\{c_0, c_1, \ldots, c_n\}$  can be developed as multinomials in the low-order traces  $\{T_0, T_1, \ldots, T_n\}$ ; specifically (look again to (2))

$$c_{0} = (-)^{n} 1$$

$$c_{1} = (-)^{n-1} T_{1}$$

$$c_{2} = (-)^{n-2} \frac{1}{2!} [T_{1}^{2} - T_{2}]$$

$$c_{3} = (-)^{n-3} \frac{1}{3!} [T_{1}^{3} - 3T_{1}T_{2} + 2T_{3}]$$

$$\vdots$$

$$c_{k} = (-)^{n-k} \frac{1}{k!} \begin{vmatrix} T_{1} & T_{2} & T_{3} & T_{4} & \cdots & T_{k} \\ 1 & T_{1} & T_{2} & T_{3} & \cdots & T_{k-1} \\ 0 & 2 & T_{1} & T_{2} & \cdots & T_{k-2} \\ 0 & 0 & 3 & T_{1} & \cdots & T_{k-3} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \cdots & T_{k-3} \\ \vdots & \vdots & \vdots & \vdots & \cdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & (k-1) & T_{1} \end{vmatrix} \quad : \quad 1 \le k \le n$$

$$\vdots$$

 $c_n = \det \mathbb{M} =$ trace-wise development of the determinant

The relevant implication is that high-order traces can be described (recursively) in terms of leading-order traces

$$T_p = f_p(T_1, T_2, \dots, T_n) \quad : \quad p > n$$

And therefore that transformations  $\mathbb{M} \longrightarrow \mathbb{M}'$  which preserve leading-order traces automatically preserve *all* traces, and have therefore the form

$$\mathbb{M} \longrightarrow \mathbb{M}' = \mathbb{S} \mathbb{M} \mathbb{S}^{-1}$$

It follows, moreover, that the eigenvalues of  $\mathbb M$  are —since they can evidently be developed as algebraic functions

$$\lambda_k(T_1, T_2, \dots, T_n)$$
 :  $k = 1, 2, \dots n$ 

of the leading-order traces—are invariant under such transformations.

<sup>&</sup>lt;sup>6</sup> See also "Some applications of an elegant formula due to V. F. Ivanoff," Notes for a seminar presented 28 May 1969 to the Applied Math Club at Portland State University, expecially page 14.

#### **Concluding remarks**

We have been concerned in these pages with a 2-dimensional problem. Our objective was to describe transformations  $\mathbb{M} \longrightarrow \mathbb{M}'$  which preserve the properties characteristic of density matrices (hermiticity, positivity and unit trace) and additionally preserve  $T_2$ , which is conventionally used to quantify the "degree of mixedness."<sup>7</sup> In two dimensions the invariance of  $T_1$  and  $T_2$  has been seen to imply the invariance of the characteristic polynomial (whence of the spectrum), of traces of *all* orders, and that

$$\mathbb{M} \longrightarrow \mathbb{M}' = \mathbb{S} \mathbb{M} \mathbb{S}^{-1} \quad \text{with} \quad \mathbb{S} \text{ unitary} \tag{14}$$

If—as we have, for expository reasons been content to assume—the elements of  $\mathbb{M}$  are real then "unitary" becomes "rotational." Elements of  $\mathbb{S} \in O(2)$  are identified by a single parameter  $\alpha$ . At (11.1) we encountered an alternative one-parameter construction

$$\begin{pmatrix} p_1 & r \\ r & p_2 \end{pmatrix} \longrightarrow \begin{pmatrix} p_1 + a & A \\ A & p_2 - a \end{pmatrix}$$

where the specific structure of A was forced by the required invariance of  $T_2$ . At (13) we describe the relationship between the parameters  $\alpha$  and a.

In n = 3 dimensions the invariance of  $T_1$  and  $T_2$  does not enforce the invariance of  $T_3$  or of higher order traces. Transformations of type (14) describe now only a *subset* of the possibilities (which is to say: if n = 3 then  $T_2$ -preserving transformations can, in general, not be presented as instances of (14)), and

$$\begin{pmatrix} p_1 & r & s \\ r & p_2 & t \\ s & t & p_3 \end{pmatrix} \longrightarrow \begin{pmatrix} p_1 + a_1 & A & B \\ A & p_2 + a_2 & C \\ B & C & p_3 + a_3 \end{pmatrix} : \begin{cases} p_1 + p_2 + p_3 = 1 \\ a_1 + a_2 + a_3 = 0 \end{cases}$$

poses a much more difficult analytical problem than the one treated here; the elements of  $\mathbb{S} \in O(3)$  are 3-parameter objects, but additional parameters enter into the construction of  $\{A, B, C\}$ . As *n* advances beyond 3 the problem becomes progressively more intractable.

$$\mathbb{R} = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0\\ 0 & \lambda_2 & \cdots & 0\\ \vdots & \vdots & \ddots & \vdots\\ 0 & 0 & \cdots & \lambda_n \end{pmatrix} \quad : \quad \text{all } \lambda_i \in [0, 1] \text{ and } \sum \lambda_1 = 1$$

from which it follows that

$$T_1 = 1 \ge T_2 \ge T_3 \ge \dots \ge T_n$$

where all inequalities become equalities if and only if  $\mathbb{R}$  refers to a pure mixture. This means that the traces  $T_{k>2}$  serve as well (if less conveniently than)  $T_2$  to quantify "degree of mixedness."

<sup>&</sup>lt;sup>7</sup> The defining properties ensure that every density matrix can be written